

# Overview of GSI

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# History

- The Spectral Statistical Interpolation (SSI) analysis system was developed at NCEP in the late 1980's and early 1990's.
- Main advantages of this system over OI systems were:
  - All observations are used at once (much of the noise generated in OI analyses was generated by data selection)
  - Ability to use forward models to transform from analysis variable to observations
  - Analysis variables can be defined to simplify covariance matrix and are not tied to model variables (except need to be able to transform to model variable)
- The SSI system was the first operational
  - variational analysis system
  - system to directly use radiances



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# History

- While the SSI system was a great improvement over the prior OI system – it still had some basic short-comings
  - Since background error was defined in spectral space – not simple to use for regional systems
  - Diagonal spectral background error did not allow much spatial variation in the background error
  - Not particularly well written since developed as a prototype code and then implemented operationally



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# History

- The Global Statistical Interpolation (GSI) analysis system was developed as the next generation global/regional analysis system
  - Wan-Shu Wu, R. James Purser, David Parrish
    - *Three-Dimensional Variational Analysis with spatially Inhomogeneous Covariances. Mon. Wea. Rev., 130, 2905-2916.*
  - Based on SSI analysis system
  - Replace spectral definition for background errors with grid point version based on recursive filters



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# History

- Used in NCEP operations for
  - Regional NMMB
  - Global
  - Hurricane
  - Real-Time Mesoscale Analysis
  - Rapid Refresh and HRRR (ESRL/GSD)
- Operational at AFWA
- GMAO collaboration
- Modification to fit into FV3, WRF and NCEP infrastructure
- Evolution to JEDI



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# History

- Code Management
  - Instituted to allow multiple people and/or groups to work on system without chaos.
  - Svn system set up at EMC – one of the first operational systems to be under code management
  - Mirror set up at DTC + annual code releases
  - Plan is to make operational instances of the code along trunk.
  - Transition to VLAB git underway in the next few weeks
  - Requires both operational centers and collaborators to change how they do business



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# General Comments

- GSI analysis code is an evolving system.
  - Scientific advances
    - situation dependent background errors -- hybrid
    - new observational (satellite especially) data
    - new analysis variables
  - Improved coding
    - Bug fixes
    - Removal of unnecessary computations, arrays, etc.
    - More efficient algorithms (MPI, OpenMP)
    - Modern programming structure (GMAO, JCSDA)
    - Generalizations of code
      - Different compute platforms
      - Different analysis variables
      - Different models
    - Improved documentation
  - Fast evolution creates difficulties for slower evolving research projects



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# General Comments

- Code is intended to be used for Operations:
  - Must satisfy coding requirements
  - Must fit into infrastructure
  - Should be kept as simple as possible
- And Research:
  - Enhance testing
  - Reduce transition to operations work/time
  - Reduce duplication of effort
  - Since operational, realistic testing with all data types



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# Simplification to 3-D for presentation

- For today's introduction, I will be talking about using the GSI for standard 3-D var. analysis. Many options available or under development
  - 4d-var
  - Hybrid assimilation
  - Observation sensitivity
  - Different minimization options
  - Additional observation types
  - SST retrieval
  - Detailed options
- Options make code more complex – difficult balance between options and simplicity and understandability



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# Basic analysis problem

$$\mathbf{J} = \mathbf{J}_b + \mathbf{J}_o + \mathbf{J}_c$$

$$\mathbf{J} = (\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + (\mathbf{H}(\mathbf{x}) - \mathbf{y}_0)^T (\mathbf{E} + \mathbf{F})^{-1} (\mathbf{H}(\mathbf{x}) - \mathbf{y}_0) + \mathbf{J}_c$$

**$\mathbf{J}$  = Fit to background + Fit to observations + constraints**

**$\mathbf{x}$  = Analysis**

**$\mathbf{x}_b$  = Background**

**$\mathbf{B}$  = Background error covariance**

**$\mathbf{H}$  = Forward model**

**$\mathbf{y}_0$  = Observations**

**$\mathbf{E} + \mathbf{F} = \mathbf{R}$  = Instrument error + Representativeness error**

**$\mathbf{J}_c$  = Constraint terms**



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# Jc term

- Currently Jc term includes 2 terms
  - Weak moisture constraint ( $q > 0, q < q_{sat}$ )
    - Can substantially slow convergence if coefficient made too large.
  - Conservation of global dry mass
    - not applicable to regional problem



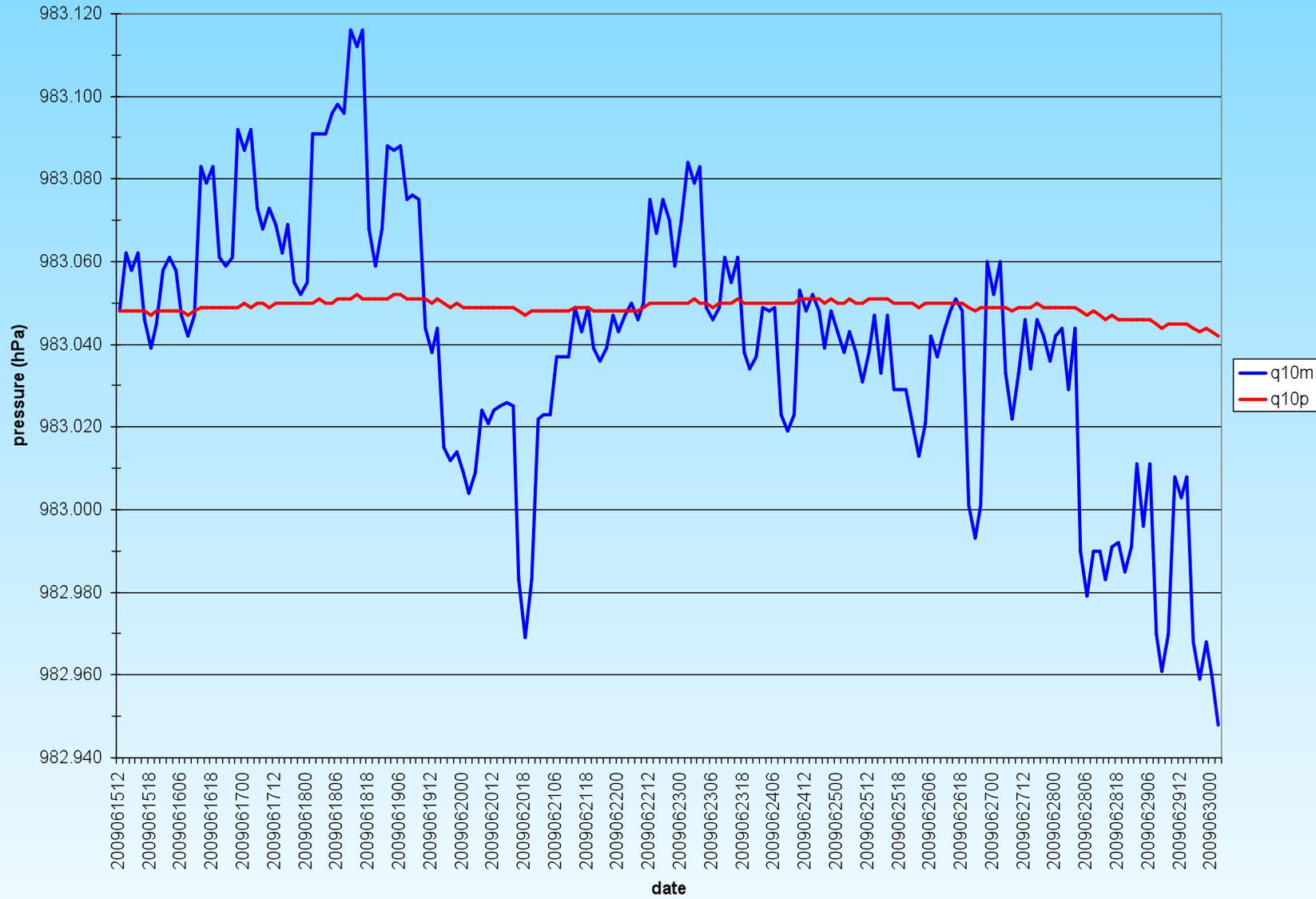
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### global mean\_pdry



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# Solution

**At minimum,  $\text{Grad } J = 0$ , Note this is a necessary condition – it is sufficient only for a quadratic  $J$**

$$\text{Grad } J = \mathbf{B}^{-1}(\mathbf{x}-\mathbf{x}_b) + \mathbf{H}^T(\mathbf{E}+\mathbf{F})^{-1}(\mathbf{H}(\mathbf{x})-\mathbf{y}_0) + \text{Grad } J_C$$

**A minimization algorithm is used to solve for  $\text{Grad } J = 0$ .**

**Definition of  $J$  primarily determines the solution, not solution algorithm.**



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# Solution Strategy

- Solve series of simpler problems with some nonlinear components eliminated
- Outer iteration, inner iteration structure
  - $x = x_{\text{outer iteration}} + x_{\text{inner iteration}} + x_b$
- Outer iteration
  - QC
  - More complete forward model
- Inner iteration
  - Several different iterative minimization options
    - Estimate search direction
    - Estimate optimal stepsize in search direction
  - Often simpler forward model
  - Variational QC
  - Solution used to start next outer iteration



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# Analysis variables

- Background errors must be defined in terms of analysis variable.
- Must be able to transform from analysis variables to model variables.
- Must be able to transform from analysis variables to observation variables.
- Variable transforms can include both statistical and dynamical (e.g., nnmi) relationships



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# Analysis variables

- Example:
  - Streamfunction ( $\Psi$ )
  - Unbalanced Velocity Potential ( $\chi_{\text{unbalanced}}$ )
  - Unbalanced Temperature ( $T_{\text{unbalanced}}$ )
  - Unbalanced Surface Pressure ( $P_{\text{s,unbalanced}}$ )
  - Ozone – Clouds – etc.
  - Satellite bias correction coefficients



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# Analysis variables

- $\chi = \chi_{\text{unbalanced}} + A \Psi$
- $T = T_{\text{unbalanced}} + B \Psi$
- $P_s = P_{s_{\text{unbalanced}}} + C \Psi$
- Streamfunction is a key variable defining a large percentage T and  $P_s$  (especially away from equator). Contribution to  $\chi$  is small except near the surface and tropopause.



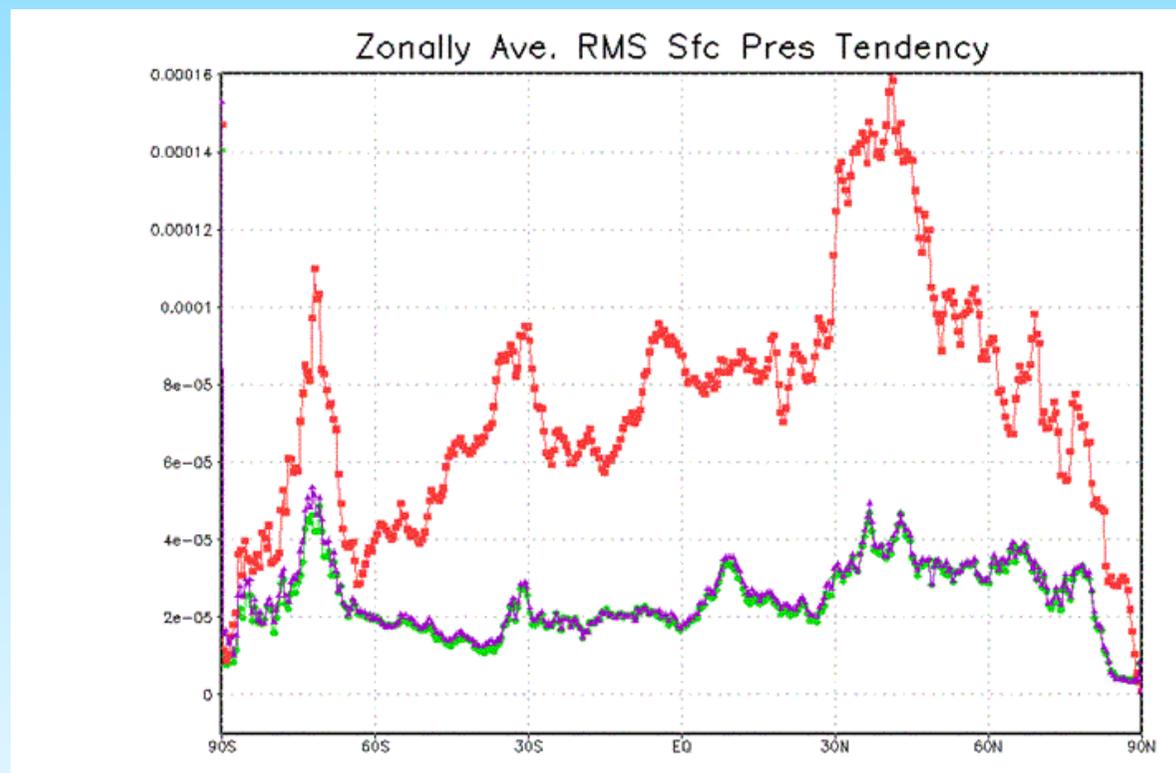
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# Impact of TLNM constraint



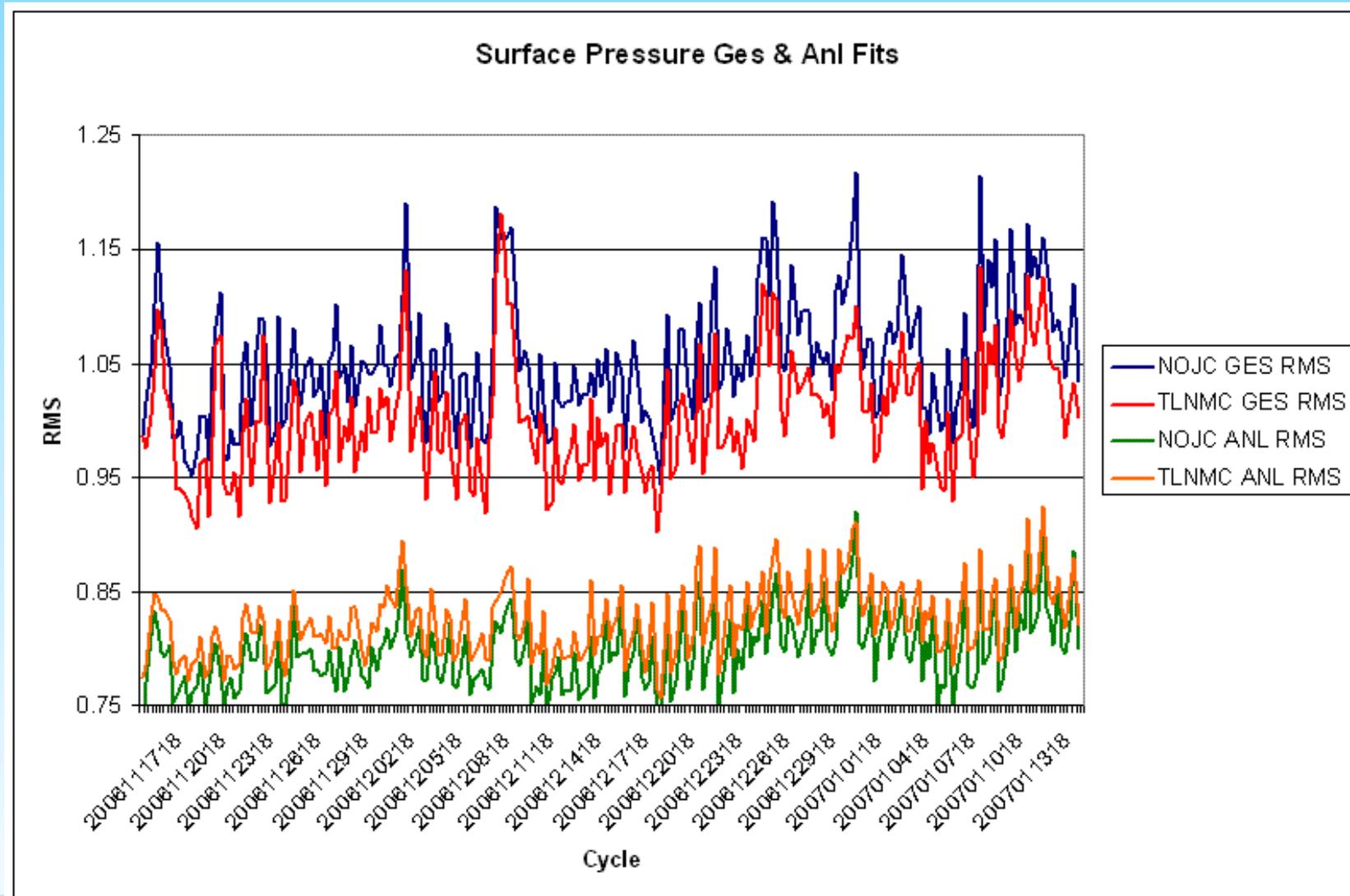
Zonal-average surface pressure tendency for background (green), unconstrained GSI analysis (red), and GSI analysis with TLNMC (purple).

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# Fits of Surface Pressure Data in Cycled Experiment with and without TLNM constraint



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# Analysis variables

- Size of problem
  - $NX \times NY \times NZ \times NVAR$
  - Global = 600 million component control vector
  - Requires multi-tasking to fit on computers
  - Also, often requires analysis increment to be done at a different resolution than the model to achieve run-time requirements.
    - GSI has 3 resolutions, analysis, background and ensemble.



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# Grid Sub-domains

- The analysis and background fields are divided across the processors in two different ways
  - Sub-Domains – an x-y region of the analysis domain with full vertical extent – observations defined on sub-domains
  - Horizontal slabs – a single or multiple levels of full x-y fields
- Since the analysis problem is a full 3-D problem – we must transform between these decompositions repeatedly



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# Background fields

- Current works for following systems
  - NCEP GFS
  - NCEP NMM(B) – binary and netcdf
  - NCEP RTMA
  - NCEP Hurricane
  - NOAA FV3 (being tested)
  - GMAO FV3 global
  - ARW – binary and netcdf
- FGAT (First Guess at Appropriate Time) enabled up to 100 time levels



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# Background Errors

- Three options
  - Isotropic/homogeneous
    - Most common usage.
    - Function of latitude/height
    - Vertical and horizontal scales separable
    - Variances can be location dependent
  - Anisotropic/inhomogeneous
    - Function of location /state
    - Can be full 3-D covariances
    - Still relatively immature
  - Hybrid
    - Includes ensembles along with one of the two options above.



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# Observations

- Observational data is expected to be in BUFR format (this is the international standard)
- Each observation type (e.g., u,v,radiance from NOAA-15 AMSU-A) is read in on a particular processor or group of processors (parallel read)
- Data thinning can occur in the reading step.
- Checks to see if data is in specified data time window and within analysis domain



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# Data processing

- Data used in GSI controlled 2 ways
  - Presence or lack of input file
  - Control files input (info files) into analysis
    - Allows data to be monitored rather than used
    - Each ob type can be specified different
      - E.g., Specify different time windows for each ob type
    - Intelligent thinning distance specification for some obs types



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# Input data – Radiance currently used

- Regional , thinned to 60km or 120km hyperspectral  
(Global. thinned to 145km)

## AMSU-A

NOAA-15	Channels 1-5,7-10, 12-13, 15
NOAA-18	Channels 1-4,6-7, 10-13, 15
NOAA-19	Channels 1-6, 9-13, 15
METOP-A	Channels 1-6, 9-13, 15
METOP-B	Channels 7-11(13)
AQUA	Channels 6, 8-13

## ATMS

NPP	Channels 1-11,16-19
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## MHS

NOAA-19	Channels 1-2,4-5
METOP-A	Channels 1-5
METOP-B	Channels 1-5

## HIRS

None

## Geo Sounder

GOES-15, all 4 sensors	Channels 1-15
SEVERI M10	Channels 2-3

## Hyperspectral

AIRS AQUA	148 Channels
IASI METOP-A	165 Channels
IASI METOP-B	165 Channels
NPP CrIS	84 Channels

## SSMIS

F17	(Channels 1-3,5-7,24)
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# Input data – Conventional currently used

- Radiosondes
- Pibal winds
- Synthetic tropical cyclone winds
- wind profilers
- conventional aircraft reports
- ASDAR aircraft reports
- MDCARS aircraft reports
- dropsondes
- MODIS IR and water vapor winds
- GMS, JMA, METEOSAT and GOES cloud drift IR and visible winds
- GOES water vapor cloud top winds
- Surface land observations
- Surface ship and buoy observation
- SSM/I wind speeds
- QuikScat and ASCAT wind speed and direction
- SSM/I and TRMM TMI precipitation estimates
- Doppler radial velocities
- VAD (NEXRAD) winds
- GPS precipitable water estimates
- GPS Radio occultation refractivity and bending angle profiles
- SBUV ozone profiles and OMI total ozone



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# Data Sub-domains

- Observations are distributed to processors they are used on. Comparison to obs are done on sub-domains.
  - If an observation is on boundary of multiple sub-domains will be put into all relevant sub-domains for communication free adjoint calculations.
  - However, it is necessary to assign the observation only to one sub-domain for the objective function calculation
  - Interpolation of sub-domain boundary observations requires the use of halo rows around each sub-domain



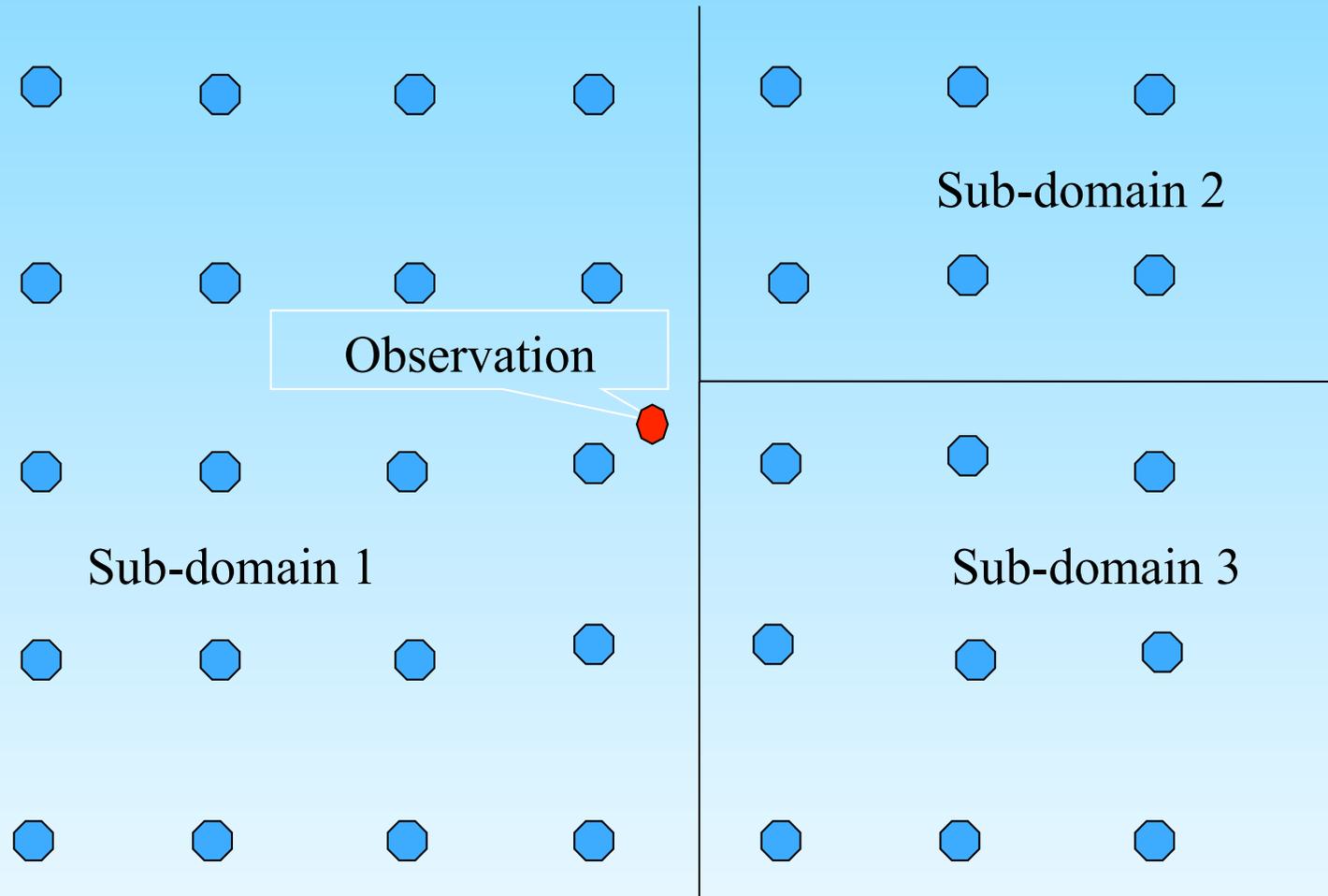
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# Observation/Sub-domain layout



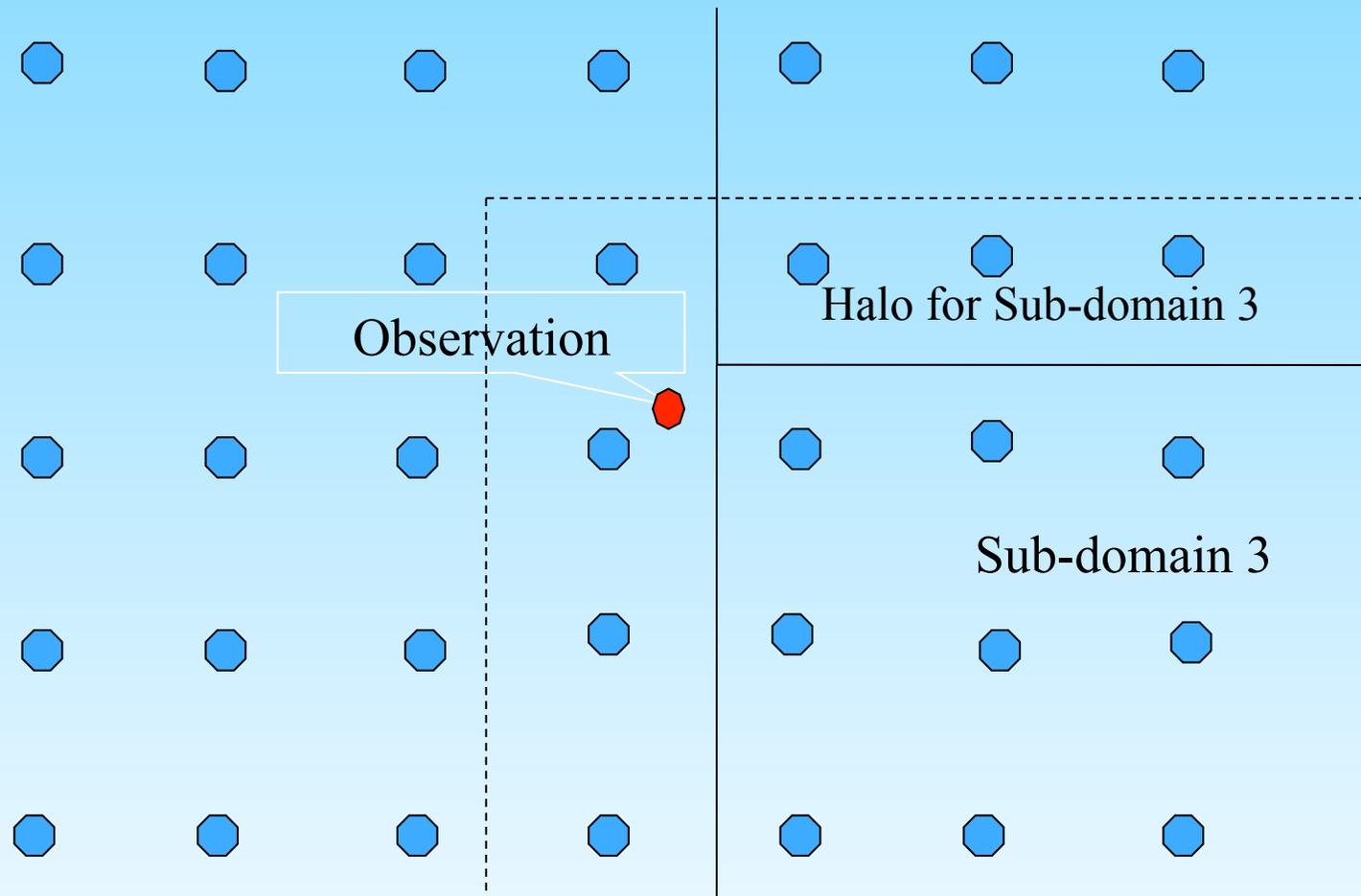
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# Sub-domain 3 calculation w/halo



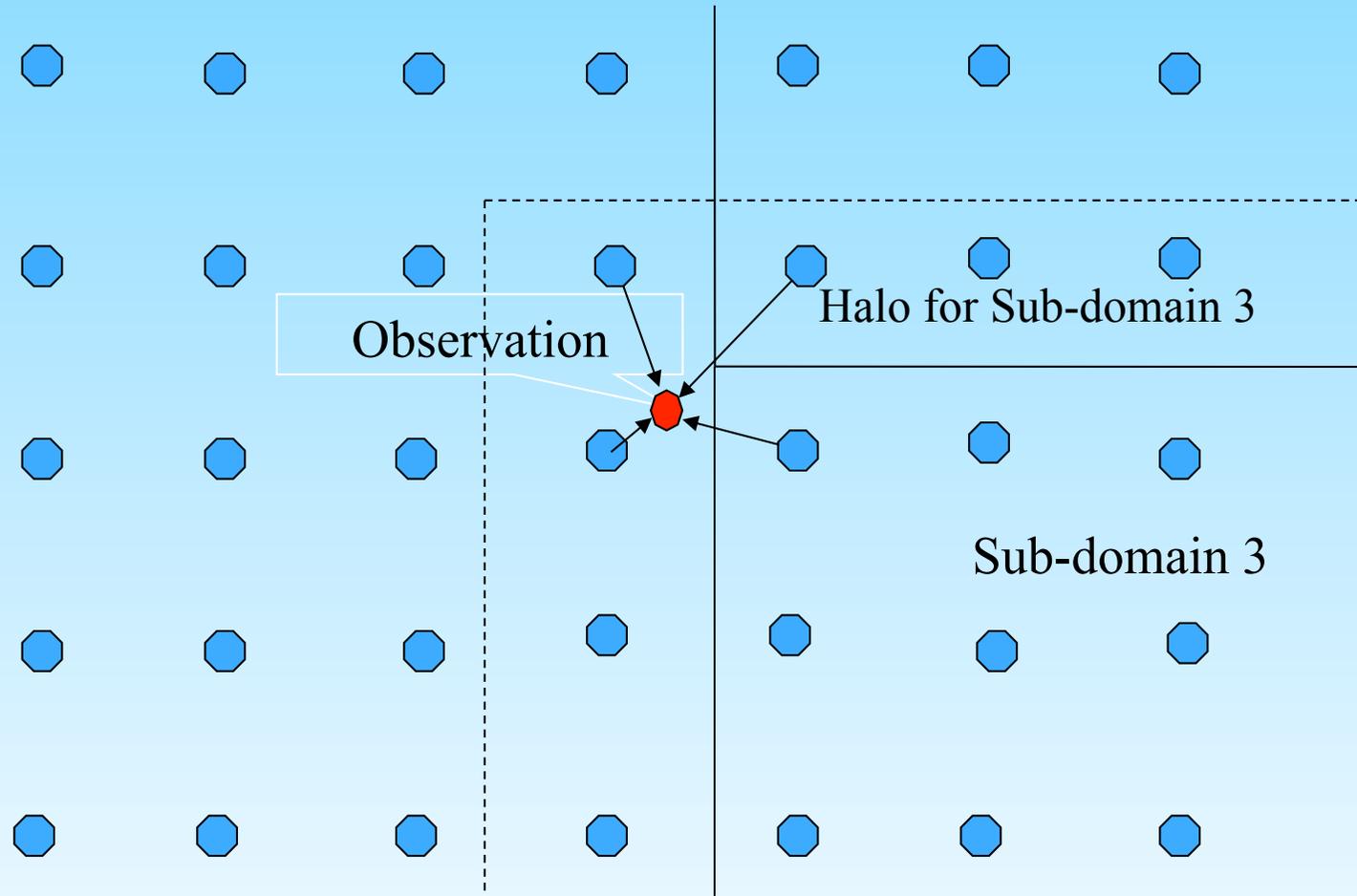
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# Forward interpolation to ob.



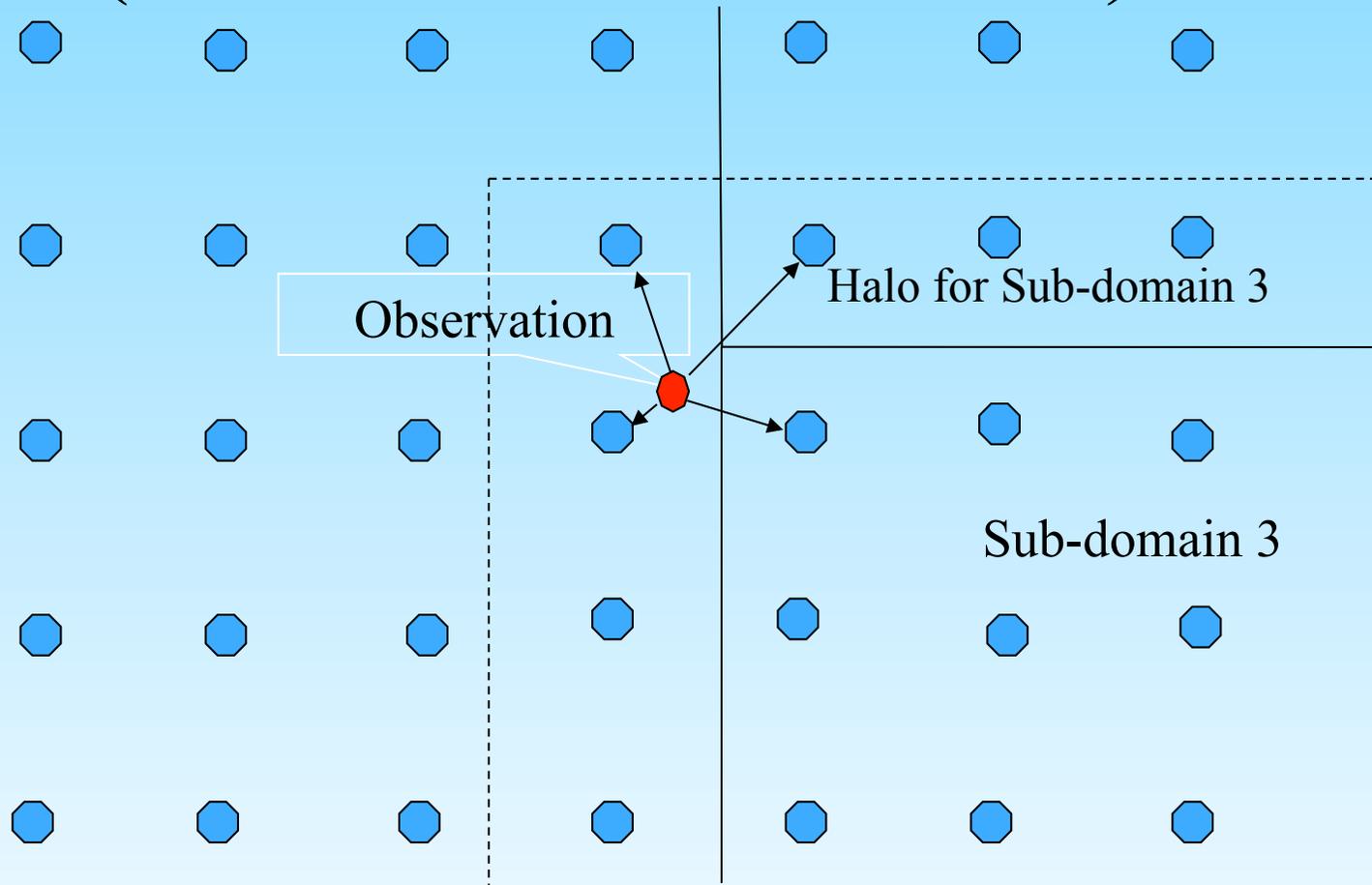
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# Adjoint of interpolation to grid (values in halo not used)



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# Simulation of observations (forward models)

- To use observation, must be able to simulate observation
  - Can be simple interpolation to ob location/time
  - Can be more complex (e.g., radiative transfer)
- For radiances we use CRTM
  - Vertical resolution and model top important



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# Atmospheric analysis problem (Practical)

## Outer ( $K$ ) and Inner ( $L$ ) iteration operators

Variable	$K$ operator	$L$ operator
Temperature – surface obs. at 2m	3-D sigma interpolation adjustment to different orography	3-D sigma interpolation Below bottom sigma assumed at bottom sigma
Wind – surface obs. at 10m over land, 20m over ocean, except scatt.	3-D sigma interpolation reduction below bottom level using model factor	3-D sigma interpolation reduction below bottom level using model factor
Ozone – used as layers	Integrated layers from forecast model	Integrated layers from forecast model
Surface pressure	2-D interpolation plus orography correction	2-D interpolation
Precipitation	Full model physics	Linearized model physics
Radiances	Full radiative transfer	Linearized radiative transfer

# Quality control

- External platform specific QC
- Some gross checking in PREPBUFR file creation
- Analysis QC
  - Gross checks – specified in input data files
  - Variational quality control
  - Data usage specification (info files)
  - Outer iteration structure allows data rejected (or downweighted) initially to come back in (GMAO option to turn off)
  - Ob error can be modified due to external QC marks
  - Radiance QC much more complicated. Tomorrow!



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# Observation output

- Diagnostic files are produced for each data type for each outer iteration (controllable through namelist)
- Output from individual processors (sub-domains) and concatenated together outside GSI
- External routines exist for reading diagnostic files



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# GSI layout (major routines) (generic names, 3dvar path)

- gsimain (main code)
  - gsimain\_initialize (read in namelists and initialize variables)
  - gsimain\_run
    - gsisub
      - deter\_subdomain (creates sub-domains)
      - \*read\_info (reads info files to determine data usage)
      - glbsoi
        - » observer\_init (read background field)
        - » observer\_set (read observations and distribute)
        - » prewgt (initializes background error)
        - » setuprhsall (calculates outer loop obs. increments)
        - » Pcgsoi, sqrtmin or other minimization (solves inner iteration)
    - writeall
  - gsimain\_finalize (clean up arrays and finalize mpi)



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# GSI layout (major routines)

- pcgsoi (other minimizations similar)
  - control2state (convert control vector to state vector)
  - intall (compare to observations and adjoint)
  - control2state\_ad (transpose of convert vector to state vector)
  - bkerror (multiply by background error)
  - stpcalc (estimate stepsize and update solution)
  - update\_guess (updates iteration solution)



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# Challenges

- Negative Moisture and other tracers
- Cloud and precipitation assimilation
- Trace gas, aerosol, land, ocean, ice, etc. assimilation
- Cross-variable covariances – “balance”
- Situation dependent background and observation errors
- Use of satellite radiances in regional mode
- Use of satellite data impacted by land/ice/snow (surface emissivity issues)



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# Useful References

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