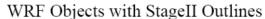
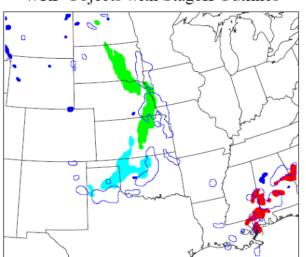
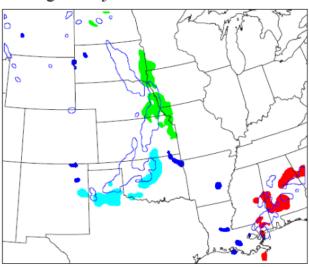
MODE Customization and Output

Verifying with Objects



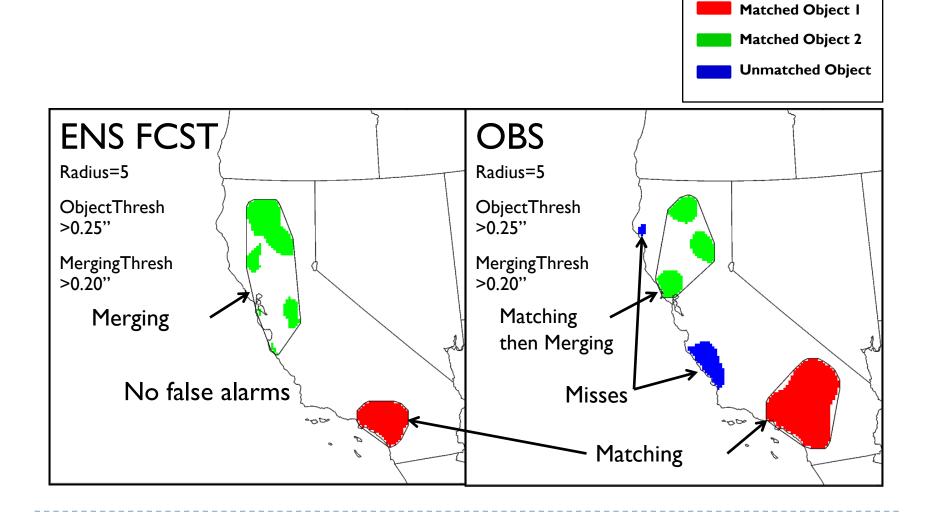


StageII Objects with WRF Outlines



Presenter: Tina Kalb

MODE Example



MODE Input and Usage

- Input Files: Gridded forecast and observation
 - GRIB1, GRIB2 (Unified Post-Processor, NCEP, other)
 - NetCDF (PCP-Combine, wrf_interp, CF-compliant)
- Usage: mode
 - fcst file
 - obs file
 - config_file
 - [-config_merge merge_config_file]
 - [-outdir path]
 - [-log file]
 - [-v level]

fcst_file	Gridded forecast file			
obs_file	Gridded observation file			
config_file	ASCII configuration file			
-config_merge	Second configuration file for fuzzy engine merging			
-outdir	Output directory to be used			
-log	Optional log file			
-V	Level of logging			

Config File

https://dtcenter.org/met/users/support/online_tutorial/METv6.1/config/MODEConfig_default

```
// Run all permutations of radius and threshold
quilt = TRUE;
// Forecast and observation fields to be verified
//
                                                                       // Handle missing data
fcst = {
  field = {
                                                                       mask_missing_flag = BOTH;
     name = "prAnom";
     level = "(*,*)";
                                                                       // Match objects between the forecast and observation fields
   file_type
                   = NETCDF_NCCF;
   censor thresh
                   = [];
                                                                       match_flag = MERGE_BOTH;
   censor_val
                   = [];
                   = [0,2,4,8]; // in grid squares
   conv_radius
   conv thresh
                   = [<=-0.5, <=-0.75, <=-1.0, <=-1.25, >=0.5, >=0.75, >=1.0, >=1.2
                                                                       // Maximum centroid distance for objects to be compared
   vld_thresh
                   = 0.5:
  area thresh
                   = NA:
                                                                       |max_centroid_dist = 800.0/grid_res;
   inten_perc_value = 100;
   inten_perc_thresh = NA;
                   merge thresh
  merge_flag
                   = ENGINE;
obs = {
                                                                       // Verification masking regions
|field = {
     name = "prAnom";
                                                                       lmask = {
     level = "(*,*)";
                                                                          grid
                                                                          grid_flag = NONE; // Apply to NONE, FCST, OBS, or BOTH
   file_type
                   = NETCDF_NCCF;
                                                                          poly_flag = NONE; // Apply to NONE, FCST, OBS, or BOTH
   censor_thresh
                   = [];
                   = [];
   censor val
   conv radius
                   = [0,2,4,8]; // in grid squares
                   = [<=-0.5,<=-0.75,<=-1.0,<=-1.25,>=0.5,>=0.75,>=1.0,>=1.25];
   conv thresh
  vld thresh
                   = 0.5:
  area thresh
                   = NA;
   inten_perc_value = 100;
   inten_perc_thresh = NA;
```

= [>=1.25,>=1.25,>=1.25,>=1.25,>=1.25,>=1.25,>=1.25,>=1.25,>=1.25];

merge_thresh

= ENGINE:

merge_flag

Config File

```
//
// Fuzzy engine weights
//
weight = {
   centroid_dist = 2.0;
   boundary_dist = 4.0;
   convex_hull_dist = 0.0;
   angle_diff = 1.0;
   area_ratio = 1.0;
   int_area_ratio = 2.0;
   complexity_ratio = 0.0;
   inten_perc_ratio = 0.0;
   inten_perc_value = 50;
```

```
//
// Total interest threshold for determining matches
//
total_interest_thresh = 0.5;
//
// Interest threshold for printing output pair information
//
print_interest_thresh = 0.0;
```

```
// Fuzzy engine interest functions
interest_function = {
  centroid dist = (
                  0.0, 1.0
       60.0/grid_res, 1.0 )
     ( 600.0/grid_res, 0.0 )
   );
  boundary_dist = (
                  0.0, 1.0
     ( 400.0/grid_res, 0.0 )
   );
  convex_hull_dist = (
                  0.0, 1.0)
     ( 400.0/grid_res, 0.0 )
   );
  angle_diff = (
     (0.0, 1.0)
     ( 30.0, 1.0 )
     (90.0, 0.0)
   );
  corner = 0.8:
   ratio if = (
          0.0, 0.0
       corner, 1.0 )
          1.0, 1.0)
   );
  area_ratio = ratio_if;
   int area ratio = (
     (0.00, 0.00)
     (0.10, 0.50)
     (0.25, 1.00)
     (1.00, 1.00)
   );
  complexity ratio = ratio if;
   inten_perc_ratio = ratio_if;
```

MODE Output

PostScript

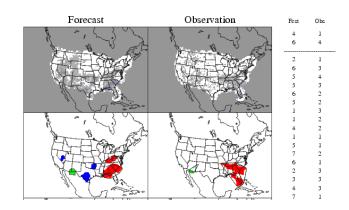
- object pictures, definitions
- matching/merging strategy
- total interest for each object pair

ASCII Text

- attributes of simple, paired objects, clusters
 - size, shape, position, separation, total interest
- verification scores (CSI, bias, etc.) for objects

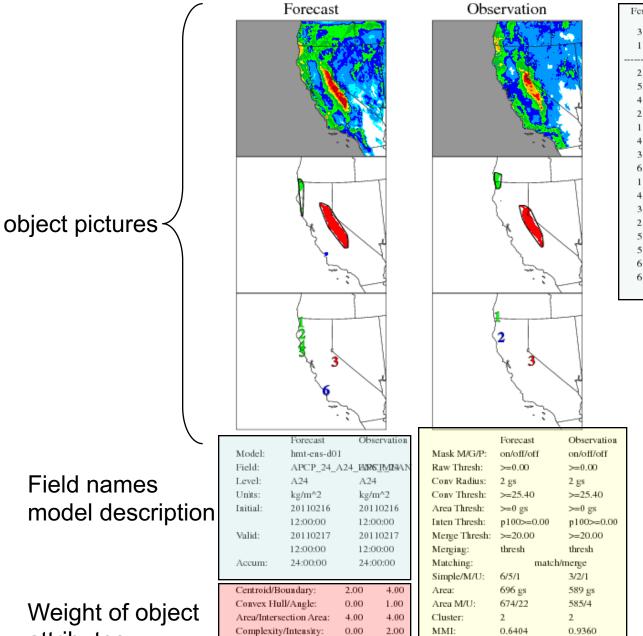
netCDF

- gridded object fields
- view with ncview



```
// NetCDF matched pairs, PostScript,
  and contingency table output files
ps_plot_flag
                = TRUE;
nc_pairs_flag
   latlon
                = TRUE;
                = TRUE;
   raw
  object_raw
                = TRUE;
  object_id
                = TRUE;
   cluster_id
                = TRUE;
   polylines
                = TRUE;
ct_stats_flag
                = TRUE:
```

IODE: APCP_24_A24_ENS_MEAN at A24 vs APCP_24 at A2



Total Interest Thresh:

0.70

MMI (F+O):

0.6436

Fest 3 3 1.0000 0.9360 2 0.6436 2 0.6372 0.5085 0.40600.38710.3545 0.34223 0.3265 3 0.3141 0.2813 0.2719 3 0.2704 0.2406 0.22660.2203 0.1936

Total Interest of object pairs

Pairs above dashed line processed further

Definition of objects

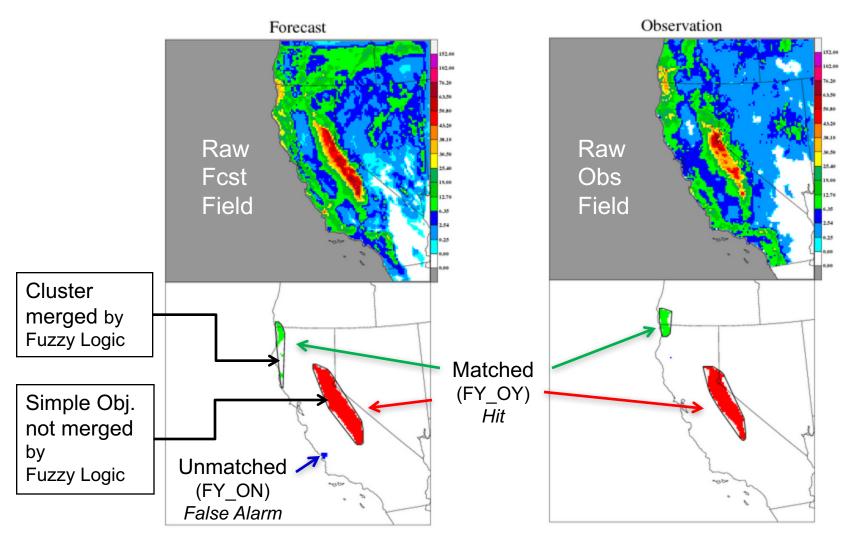
- smoothing radius
- intensity threshold
- area threshold
- matching and/or merging
- # and area of objects
- Median Max. Interest (MMI)

attributes

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Page 2 and 3 of PostScript:

- •Band shows which Simple Objects are merged (aka Cluster)
- Colors show matching between Fcst and Obs.

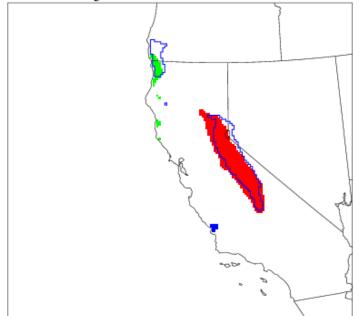


Page 4 of PostScript

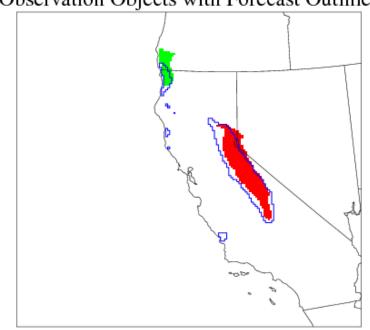
Objects overlapped In two different views...

Which do you prefer?



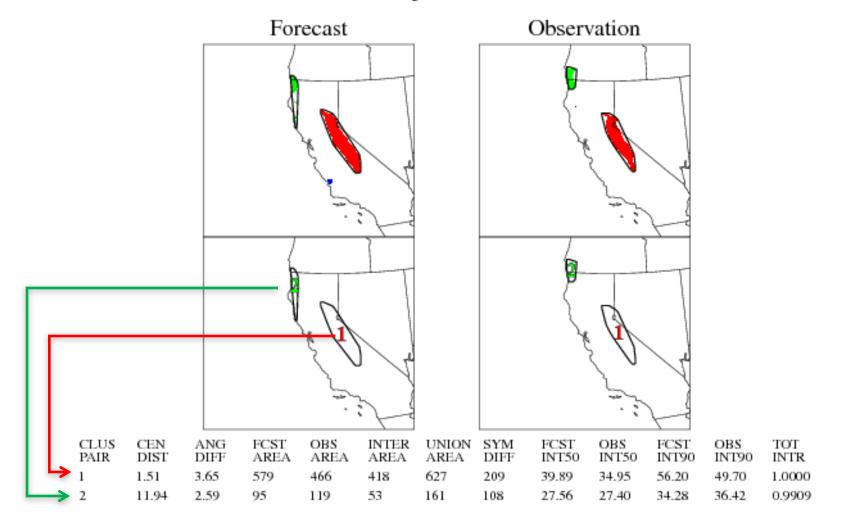


Observation Objects with Forecast Outlines



Page 5 of PostScript - Summary information for clusters in the domain

Cluster Object Information



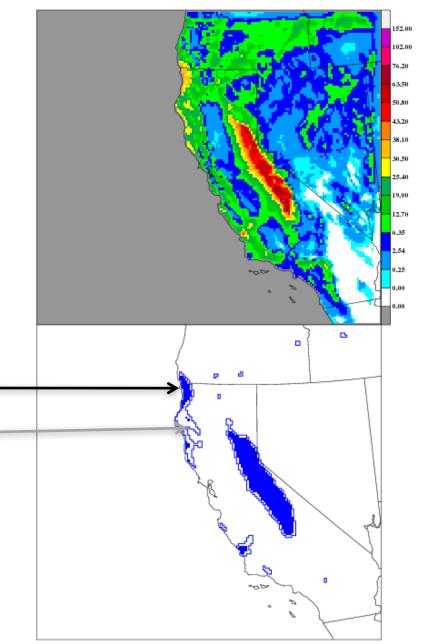
Page 6+ of PostScript

Raw Field and Double Thresholding For Merging Process

Convolution Threshold (>=25.4mm)

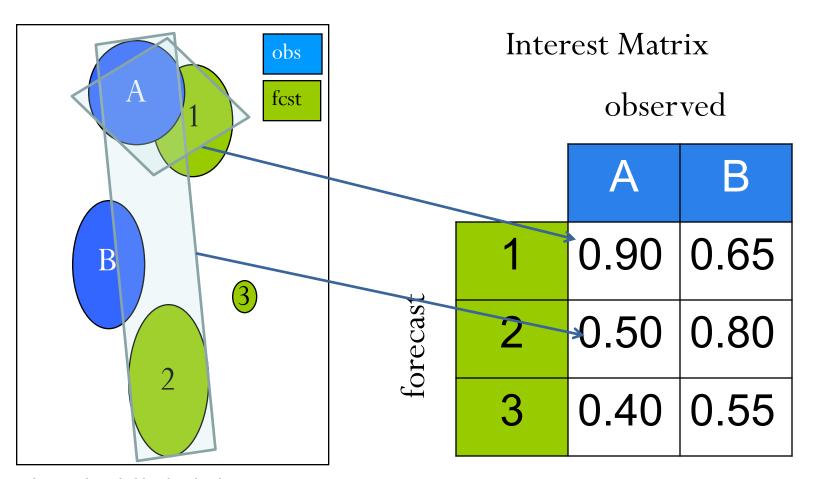
Double Thresholding Value (>=22.5mm)

Forecast: Threshold Merging



Summary Score for Forecast

Median of the Max. Interest (MMI*)

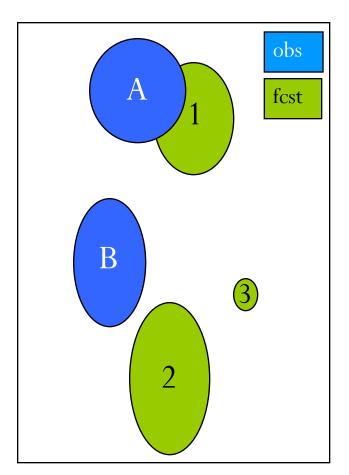


^{*} Davis et al., 2009: The Method for Object-based Diagnostic Evaluation (MODE) Applied to WRF Forecasts from the 2005 SPC Spring Program. Weather and Forecasting

MMI = median $\{0.90, 0.80, 0.90, 0.80, 0.55\} = 0.80$ copyright 2018, UCAR, all rights reserved

Summary Score for Forecast

Median of the Max. Interest (MMI*)



Interest Matrix

observed

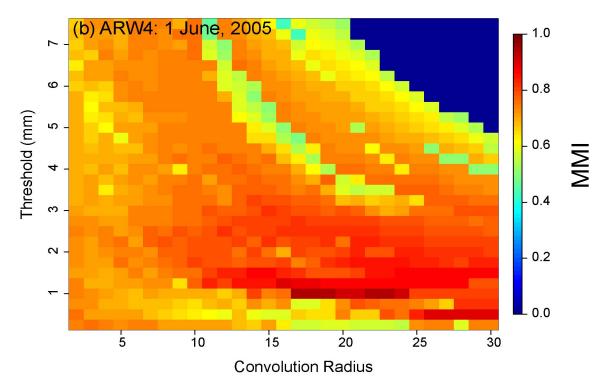
	A			В
1_	0.9	0_	0	.65_
2	0.5	0_	0	.80_
3	0.4	Q	0	.55_

 $MMI = \text{median} \{0.90, 0.80, 0.90, 0.80, 0.55\} = 0.80$

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^{*} Davis et al., 2009: The Method for Object-based Diagnostic Evaluation (MODE) Applied to WRF Forecasts from the 2005 SPC Spring Program. Weather and Forecasting

Median of the Max. Interest (MMI) Quilt Plot



MMI as a function of convolution radius (grid squares) and threshold (mm) for 24-h forecast of 1-h rainfall

- Each pixel is a MODE run.
- This graphic is not in MET, but R code on MET website.

MODE Output

PostScript

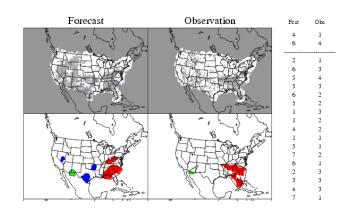
- object pictures, definitions
- matching/merging strategy
- total interest for each object pair

ASCII Text

- attributes of simple, paired objects, clusters
 - size, shape, position, separation, total interest
- verification scores (CSI, bias, etc.) for objects

netCDF

- gridded object fields
- view with neview



```
// NetCDF matched pairs, PostScript,
  and contingency table output files
ps_plot_flag
                = TRUE;
nc_pairs_flag
   latlon
                = TRUE;
                = TRUE;
   raw
  object_raw
                = TRUE;
  object_id
                = TRUE;
   cluster_id
                = TRUE;
   polylines
                = TRUE;
ct_stats_flag
                = TRUE:
```

ASCII Output

Object Attribute file (*_obj.txt)

- Header with fields names and object definition info
- Object ID and Category
- Simple Object Attributes
 - Simple Obj. Centroid info, Length,
 Width, Area, etc...
- Matched Pair/Composite information
 - Centroid Distance, Angle
 Difference, Symmetric Difference,
 etc...
- NA's for not relevent output

Contingency Table Stat file (*_cts.txt)

- Header with fields names and object definition info
- Contingency Table counts
 - hits, false alarms, misses and correct negs (FY|FN_OY|ON notation)
- Contingency Table statistics such
 - BASER, FBIAS, GSS, CSI, PODY, FAR etc...

ASCII Output

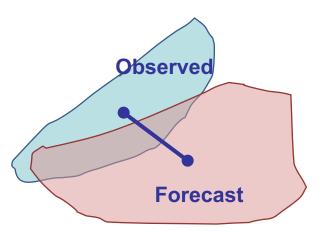
Object Attribute file (*_obj.txt)

OBJECT_ID	OBJECT_CAT	CENTROID_X	CENTROID_Y	CENTROID_LAT	CENTROID_LON	AXIS_ANG	LENGTH	WIDTH	AREA
F001	CF000	1088.10939	419.8381	35.38308	-91.24656	35.0499	159.73583	69.37881	6625
0001	C0000	1072.24122	767.62874	44.75884	-90.95277	48.23578	202.68348	82.43007	10024
0002	C0000	899.80285	567.40078	39.53595	-97.47192	48.70561	39.12947	25.76823	707
F001_0001	CF000_C0000	NA	NA	NA	NA	NA	NA	NA	NA
F001_0002	CF000_C0000	NA	NA	NA	NA	NA	NA	NA	NA

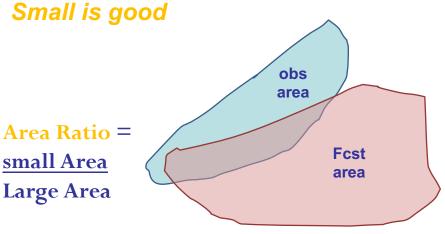
Contingency Table Stat file (*_cts.txt)

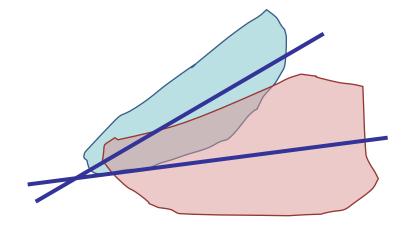
OBTYPE	FIELD	TOTAL	FY_OY	FY_ON	FN_OY	FN_ON	BASER	FMEAN	ACC	FBIAS	PODY	PODN	POFD	FAR	CSI
GPCP	RAW	1714176	51313	51666	95113	1516084	0.085421	0.060075	0.91437	0.70328	0.35044	0.96704	0.032956	0.50171	0.25904
GPCP	OBJECT	1714176	48522	49626	82152	1533876	0.076231	0.057257	0.92312	0.75109	0.37132	0.96866	0.031339	0.50562	0.26912

Use of MODE Pair Attributes



Centroid Distance: Quantitative measure of forecast spatial Displacement.





Axis Angle: For non-circular Objects, measure of orientation errors.

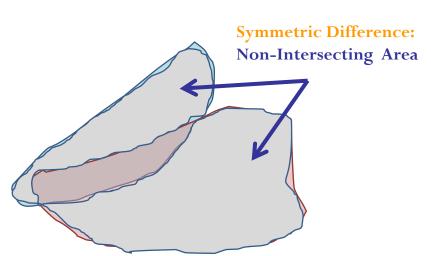
Small is good

Area Ratio: Provides an objective measure of whether there is an over- or underprediction of areal extent of forecast.

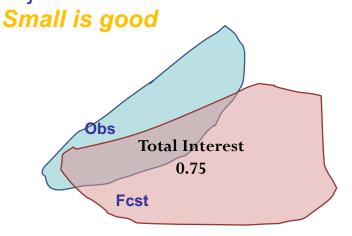
Close to 1 is good

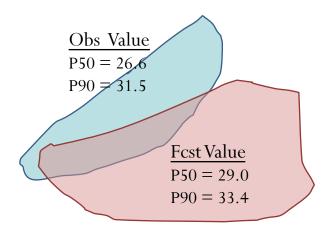
copyright 2018, UCAR, all rights reserved

Use of MODE Pair Attributes



Symmetric Diff: Summary statistic for how well Forecast and Observed objects match.

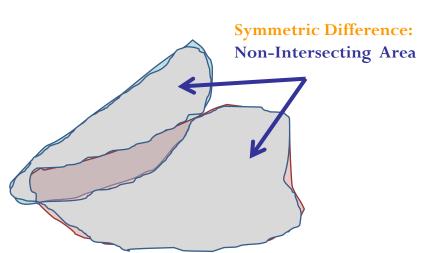




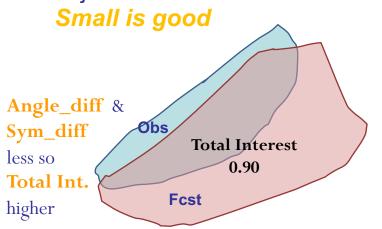
P50 | P90 Int: Objective measures of Median (50th percentile) and near-Peak (90th percentile) intensities in objects. *Ratio close To 1 is good*

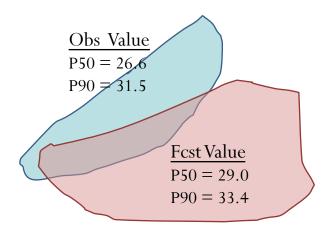
Total Interest: Summary statistic derived from fuzzy logic engine with user-defined Interest Maps for all these attributes plus some others. *Close to 1 is good*

Use of MODE Pair Attributes



Symmetric Diff: Summary statistic for how well Forecast and Observed objects match.





P50 | P90 Int: Objective measures of Median (50th percentile) and near-Peak (90th percentile) intensities in objects. *Ratio close To 1 is good*

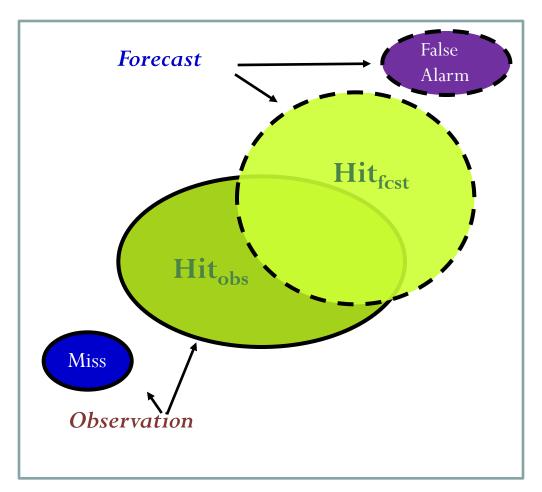
Total Interest: Summary statistic derived from fuzzy logic engine with user-defined Interest Maps for all these attributes plus some others. *Close to 1 is good*

Scoring MODE Objects

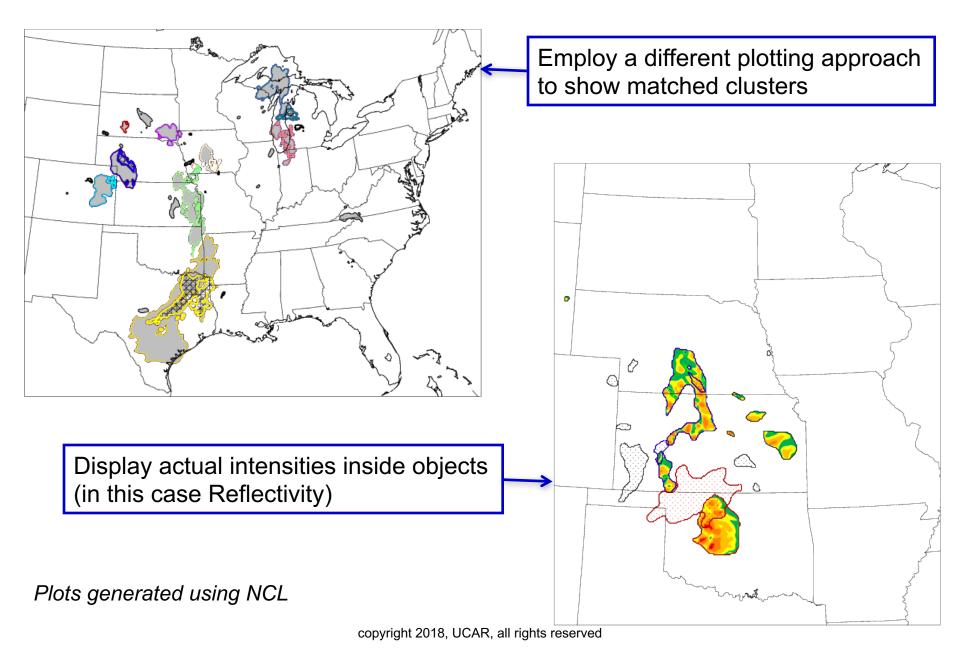
use total interest threshold to separate matched objects, or "hits" from false alarms and misses

Traditional Categorical Statistics

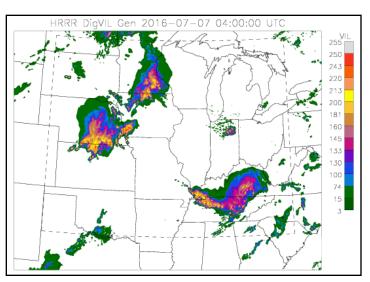
sometimes area-weighted

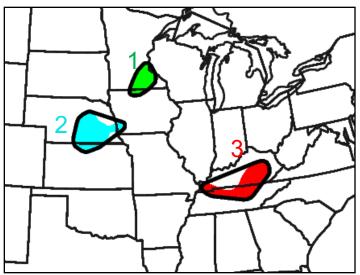


How netCDF could be used



MODE Example: Traditional



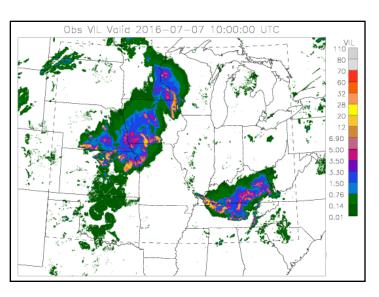


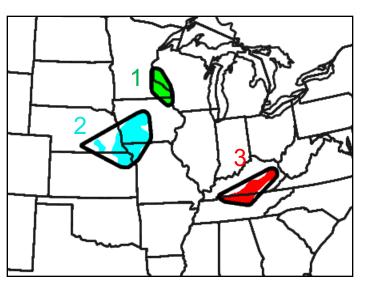
Object #3

Fcst Area: 6302 Obs Area: 4020 Centroid Dist: 12.4

Int Area: 3189

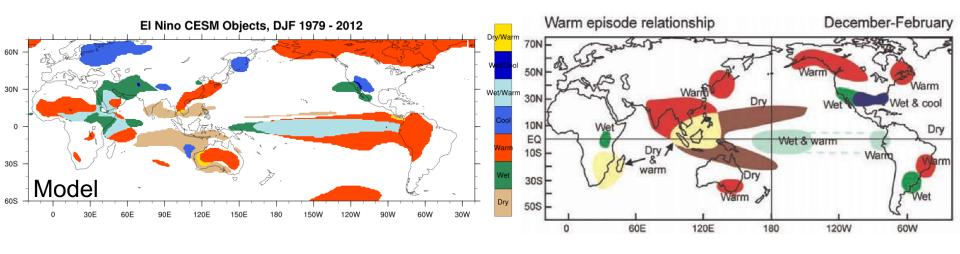
Interest: 0.98

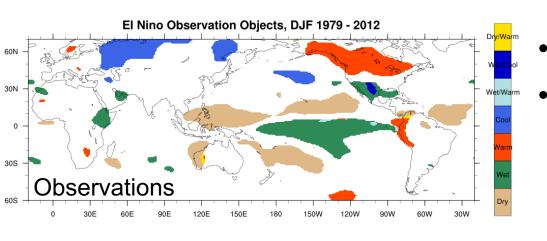




No False alarms or misses

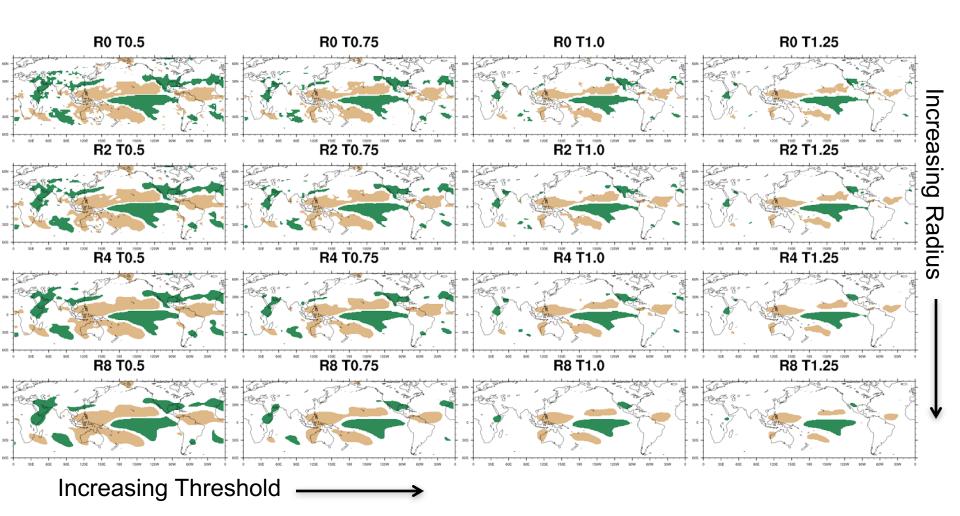
MODE Example: El Nino Climate





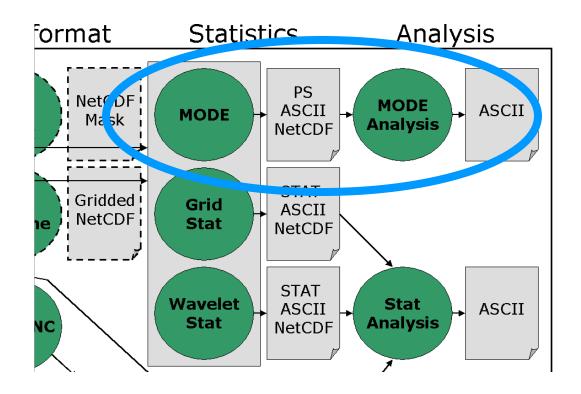
- Not individual forecasts
- Quantify differences in each anomaly type separately

Effect of Radius and Threshold



MODE Analysis Tool

mode_analysis



MODE_Analysis Usage

```
Usage: mode analysis
      -lookin path
      -summary or -bycase
      [-column name]
      [-dump_row filename]
      [-out filename]
      [-log filename]
      [-v level]
      [-help]
      [MODE FILE LIST]
      [-config config file]
      or [MODE LINE OPTIONS]
```

MODE LINE OPTIONS

Object Toggles

-fcst versus -obs

Selects lines pertaining to forecast objects or observation objects

-single versus -pair

Selects single object lines or pair lines

-simple versus -cluster

Selects simple object lines or cluster

-matched versus -unmatched

Selects matched simple object lines or unmatched simple object lines.

Other Options (each option followed by value)

- -model, -fcst|obs_thr , -fcst_var , etc...
- -area_min|max, -intersection_area_min|max, etc...
- -centroid_x_min|max , -centroid_y_min|max,
 - -axis_ang_min|max, -int10_min|max,
 - -centroid_dist_min|max, -angle_diff_min|max,
 etc...

MODE_Analysis Config File

// MODE line type toggle options

```
//
                                            fcst
                                                      = FALSE;
                                            obs
                                                         = FALSE;
// Integer min/max options
//area min
                  = 0:
                  = 0;
//area_max
//area filter min
                  = 0:
//area filter max
                  = 0;
                                               // Multiple set string options
//area thresh min
                  = 0:
                                                //
//area thresh max
                  = 0;
                                                //model = [];
//intersection area min = 0;
                                               //desc = [];
//intersection area max = 0;
                                               //fcst thr = [];
//union area min
                  = 0:
//union area max
                  = 0;
                                                //obs thr = [];
                                                //fcst var = [];
//symmetric diff min
                  = 0:
//symmetric diff max
                  = 0;
                                                //fcst_lev = [];
                                               //obs_var = [];
//obs lev = [];
// Date/time min/max options
// Date/time strings of the form YYYYMMDD, YYYYMMDD HH, or YYYYMMDD HHMMSS
//fcst valid min = "":
//fcst valid max = "";
```

MODE Analysis Tool -summary Example

Command Line

```
mode_analysis -summary \
    -lookin mode_output/wrf4ncep/40km/ge03.\
    -fcst -cluster \
    -area_min 100 \
    -column centroid_lat -column centroid_lon \
    -column area \
    -column axis_ang \
    -column length
```

Provides summary statistics for Forecast Clusters with minimum area of 100 grid-sq for the specified MODE output columns

Output

```
Total mode lines read = 393
Total mode lines kept = 17
```

Field	N	Min	Max	Mean	StdDev	P10	P25	P50	P75	P90	Sum
centroid_lat	17	31.97	46.24	38.65	3.81	33.89	36.13	38.54	40.12	43.99	657.00
centroid_lon	17	-103.89	-85.20	-96.32	5.91	-103.15	-102.65	-96.26	-93.95	-86.78	-1637.49
area	17	180.00	8393.00	2955.06	2246.49	624.80	1206.00	2662.00	3958.00	5732.20	50236.00
axis_ang	17	-88.63	85.66	12.62	64.35	-70.77	-63.86	35.04	74.37	79.24	214.60
length	17	25.25	234.76	124.41	60.99	48.85	65.37	116.67	169.37	204.57	2114.90

MODE Analysis Tool -bycase Example

Command Line

mode_analysis -bycase -lookin mode_output/wrf4ncep/40km/ge03. -single -simple

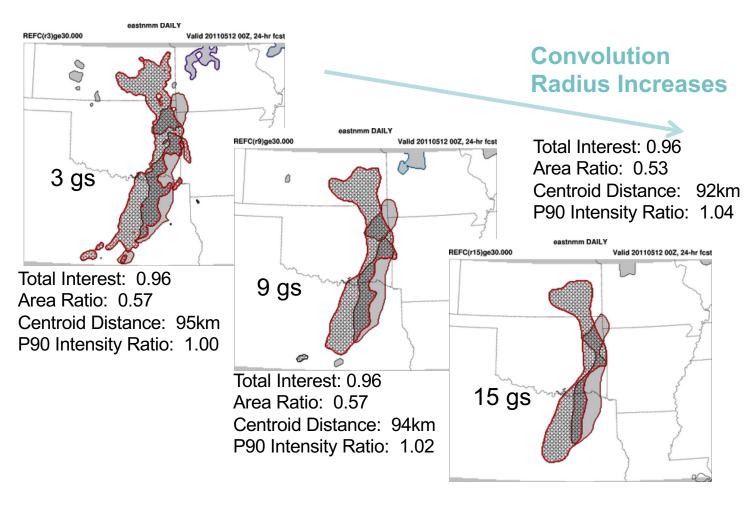
Output

Total mode lines read = 393 Total mode lines kept = 141

Fcst Valid Time	Area Matched Area	Unmatched #	Fcst Matched #	Fcst Unmatched # Ob	s Matched # Ob:	s Unmatched
Apr 26, 2005 00:00:00	3210	1046	2	4	1	1
May 13, 2005 00:00:00	8892	9320	2	19	1	2
May 14, 2005 00:00:00	16994	4534	7	4	5	3
May 18, 2005 00:00:00	6057	852	3	2	2	1
May 19, 2005 00:00:00	1777	1624	1	5	2	1
May 25, 2005 00:00:00	8583	928	4	2	4	2
Jun 1, 2005 00:00:00	12456	2657	5	6	6	2
Jun 3, 2005 00:00:00	7561	102	11	1	5	0
Jun 4, 2005 00:00:00	11464	5715	6	12	4	3

Provides tallied information for all Simple Objects for each case in directory

Example – REFC > 30 dBZ – Impact of smoothing radius



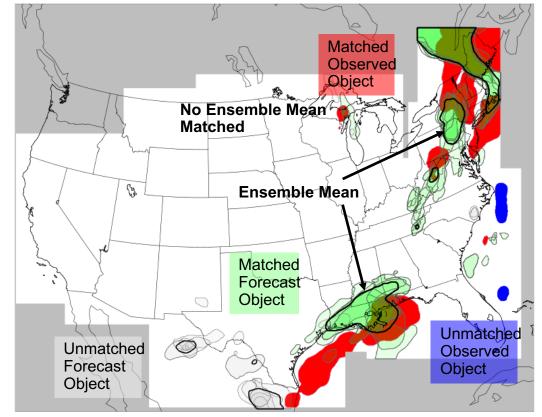
Example May 11, 2013

DTC SREF
Tests – ARW
Members

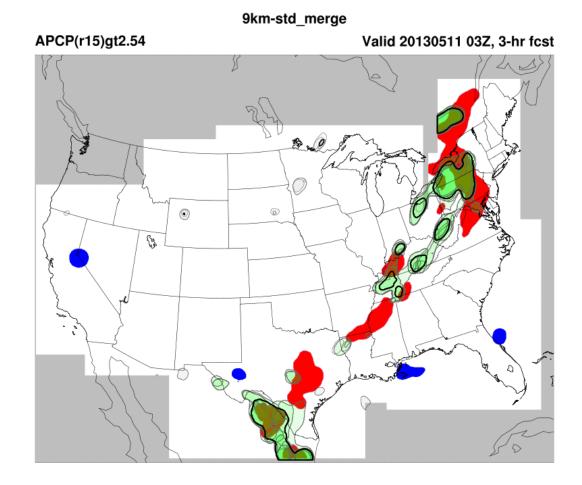
Developmental Testbed Center

9km-std_merge

APCP(r15)gt2.54 Valid 20130511 15Z, 15-hr fcst

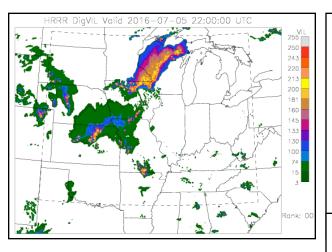


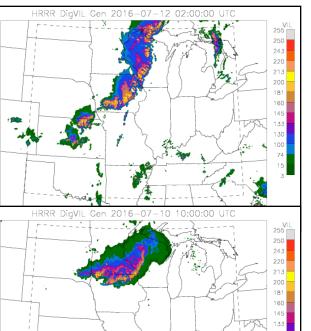
Spread increases With Time





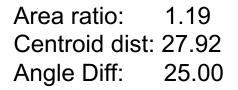
MODE Example: Fcst Analogs





HRRR DigVIL Gen 2016-07-03 05:00:00 UTC

不引 為



Area ratio: 0.81 Centroid dist: 58.15 Angle Diff: 20.41

Area ratio: 1.09 Centroid dist: 205.00 Angle Diff: 34.20